

DYNAMICAL BIFURCATIONS OF LOW-DIMENSIONAL SYSTEMS

Scope:

- To show how to apply the MSM to analyze multiple bifurcations of simple low-dimensional systems;
- To show general results, valid also for systems of arbitrary dimensions.

Outline:

- 1.** Simple-Hopf bifurcation (codimension-1).
- 2.** Non-resonant Double-Hopf bifurcation (codimension-2).
- 3.** Divergence-Hopf bifurcation (codimension-2)
- 4.** 1:1 (not generic) and 1:3 resonant double-Hopf bifurcations (codimension-3)
- 5.** 1:2 resonant double-Hopf bifurcations (codimension-3)
- 6.** Defective bifurcation: the double-zero bifurcation (codimension-2)
- 7.** Defective bifurcation: the 1:1 (generic) resonant double-Hopf bifurcation (codimension-3).

1. SIMPLE-HOPF BIFURCATION

EXAMPLE: TWO RAYLEIGH-DUFFING OSCILLATORS, ONE STABLE, THE OTHER UNSTABLE

$$\begin{cases} \ddot{x} - \mu \dot{x} + \omega_1^2 x + b_1 \dot{x}^3 + cx^3 - b_0(\dot{y} - \dot{x})^3 = 0 \\ \ddot{y} + \xi \dot{y} + \omega_2^2 y + b_2 \dot{y}^3 + cy^3 + b_0(\dot{y} - \dot{x})^3 = 0 \end{cases}$$

with $\xi > 0$.

- Discussion on stability:

When $\mu < 0$ the origin is stable. When μ crosses the bifurcation value $\mu_c = 0$, the origin becomes unstable. The system undergoes a Hopf bifurcation. Although the y -oscillator is stable, it contributes to the motion.

- Rescaling:

$$\mu \rightarrow \varepsilon\mu , \quad (x, y) \rightarrow (\varepsilon^{1/2}x, \varepsilon^{1/2}y)$$

- Series expansions:

$$\begin{pmatrix} x(t; \varepsilon) \\ y(t; \varepsilon) \end{pmatrix} = \begin{pmatrix} x_0(t_0, t_1, t_2, \dots) \\ y_0(t_0, t_1, t_2, \dots) \end{pmatrix} + \varepsilon \begin{pmatrix} x_1(t_0, t_1, t_2, \dots) \\ y_1(t_0, t_1, t_2, \dots) \end{pmatrix} + \varepsilon^2 \begin{pmatrix} x_2(t_0, t_1, t_2, \dots) \\ y_2(t_0, t_1, t_2, \dots) \end{pmatrix} + \dots$$

where $t_k := \varepsilon^k t_k$.

- Chain rule:

$$\frac{d}{dt} = d_0 + \varepsilon d_1 + \varepsilon^2 d_2 + \dots, \quad \frac{d^2}{dt^2} = d_0^2 + 2\varepsilon d_0 d_1 + \varepsilon^2 (d_1^2 + 2d_0 d_2) + \dots$$

where $d_k := \partial / \partial t_k$.

- Perturbation equations:

$$\varepsilon^0 : \begin{cases} d_0^2 x_0 + \omega_1^2 x_0 = 0 \\ d_0^2 y_0 + \xi d_0 y_0 + \omega_2^2 y_0 = 0 \end{cases}$$

$$\varepsilon^1 : \begin{cases} d_0^2 x_1 + \omega_1^2 x_1 = -2d_0 d_1 x_0 - b_1 (d_0 x_0)^3 - c x_0^3 + b_0 (d_0 y_0 - d_0 x_0)^3 + \mu d_0 x_0 \\ d_0^2 y_1 + \xi d_0 y_1 + \omega_2^2 y_1 = -2d_0 d_1 y_0 - b_2 (d_0 y_0)^3 - c y_0^3 - b_0 (d_0 y_0 - d_0 x_0)^3 - \xi d_1 y_0 \end{cases}$$

$$\varepsilon^2 : \begin{cases} d_0^2 x_2 + \omega_1^2 x_2 = -(2d_0 d_2 x_0 + d_1^2 x_0 + 2d_0 d_1 x_1) - 3b_1 (d_0 x_0)^2 (d_1 x_0 + d_0 x_1) \\ \quad - 3c x_0^2 x_1 + 3b_0 (d_0 y_0 - d_0 x_0)^2 (d_0 y_1 + d_1 y_0 - d_0 x_1 - d_1 x_0) \\ \quad + \mu (d_1 x_0 + d_0 x_1) \\ d_0^2 y_2 + \xi d_0 y_2 + \omega_2^2 y_2 = -(2d_0 d_2 y_0 + d_1^2 y_0 + 2d_0 d_1 y_1) - 3b_2 (d_0 y_0)^2 (d_1 y_0 + d_0 y_1) \\ \quad - 3c y_0^2 y_1 - 3b_0 (d_0 y_0 - d_0 x_0)^2 (d_0 y_1 + d_1 y_0 - d_0 x_1 - d_1 x_0) \\ \quad - \xi (d_2 y_0 + d_1 y_1) \end{cases}$$

- Generating solution:

$$x_0 = A(t_1, t_2) e^{i\omega_1 t_0} + c.c., \quad y_0 = 0$$

since the y -oscillator is damped. Therefore: $x = \text{active coordinate}$, and $y = \text{passive coordinate}$.

- ϵ -order:

➤ equations:

$$\begin{cases} d_0^2 x_1 + \omega_1^2 x_1 = f_{1,1} e^{i\omega_1 t_0} + f_{1,3} e^{3i\omega_1 t_0} + c.c. \\ d_0^2 y_1 + \xi d_0 y_1 + \omega_2^2 y_1 = f_{2,1} e^{i\omega_1 t_0} + f_{2,3} e^{3i\omega_1 t_0} + c.c. \end{cases}$$

where:

$$f_{1,1} := -2i\omega_1 d_1 A + i\mu\omega_1 A - 3[c + i(b_0 + b_1)\omega_1^3]A^2\bar{A},$$

$$f_{1,3} := [-c + i(b_0 + b_1)\omega_1^3]A^3$$

$$f_{2,1} := 3ib_0\omega_1^3 A^2\bar{A}, \quad f_{2,3} := -ib_0\omega_1^3 A^3$$

➤ elimination of resonant terms requires $f_{1,1} = 0$, from which:

$$d_1 A = \frac{1}{2} \mu A + \frac{3}{2} \left[i \frac{c}{\omega_1} - (b_0 + b_1) \omega_1^2 \right] A^2 \bar{A}$$

The y -equation, does not require any additional condition.

➤ Solution:

$$x_1 = -\frac{f_{1,3}}{8\omega_1^2} e^{3i\omega_1 t_0} + c.c.,$$

$$y_1 = \frac{f_{2,1}}{\omega_2^2 - \omega_1^2 + i\xi\omega_1} e^{i\omega_1 t_0} + \frac{f_{2,3}}{\omega_2^2 - 9\omega_1^2 + 3i\xi\omega_1} e^{3i\omega_1 t_0} + c.c.$$

□ **Note:** Only the particular solutions have been considered, since the complementary x -solution repeats the generating one, and the complementary y -solution decays in time.

- ε^2 -order:

➤ equations:

$$\begin{aligned} d_0^2 x_2 + \omega_1^2 x_2 = & -(2d_0 d_2 x_0 + d_1^2 x_0 + 2d_0 d_1 x_1) - 3b_1(d_0 x_0)^2 (d_1 x_0 + d_0 x_1) \\ & - 3c x_0^2 x_1 + 3b_0(d_0 x_0)^2 (d_0 y_1 - d_0 x_1 - d_1 x_0) + \mu(d_1 x_0 + d_0 x_1) \end{aligned}$$

The $d_1^2 x_0$ term requires evaluation of :

$$\begin{aligned} d_1^2 A &= \frac{1}{2} \mu d_1 A + \frac{3}{2} \left[i \frac{c}{\omega_1} - (b_0 + b_1) \omega_1^2 \right] (2A\bar{A} d_1 A + A^2 d_1 \bar{A}) \\ &= \frac{1}{4} \mu^2 A - 3\mu(b_0 + b_1) \omega_1^2 A^2 \bar{A} \\ &\quad - \frac{9}{4} \frac{c^2}{\omega_1^2} - 9i(b_0 + b_1)c\omega_1 + \frac{27}{4}(b_0 + b_1)^2 \omega_1^4 A^3 \bar{A}^2 \end{aligned}$$

➤ elimination of secular terms:

$$\begin{aligned}
 d_2 A = & -i \frac{\mu^2}{8\omega_1} A - \frac{3}{4} \frac{c}{\omega_1^2} \mu A^2 \bar{A} \\
 & + \left[-\frac{3}{2} c(b_0 + b_1) - i \frac{15}{16} \frac{c^2}{\omega_1^3} + \frac{9}{16} i \omega_1^3 (b_0 + b_1)^2 \right. \\
 & + 9ib_0^2 \omega_1^5 \left(\frac{1}{2} \frac{1}{\omega_2^2 - 9\omega_1^2 + 3i\xi\omega_1} \right. \\
 & \left. \left. + \frac{1}{\omega_2^2 - \omega_1^2 + i\xi\omega_1} - \frac{1}{2} \frac{1}{\omega_2^2 - \omega_1^2 - i\xi\omega_1} \right) \right] A^3 \bar{A}^2
 \end{aligned}$$

- Reconstitution method and parameter reabsorbing:

$$\dot{A} = \varepsilon d_1 A + \varepsilon^2 d_2 A$$

This equation is multiplied by $\varepsilon^{1/2}$ and quantities transformed back as $\varepsilon^{1/2}A \rightarrow A$, $\varepsilon\mu \rightarrow \mu$, thus obtaining a *complex bifurcation equation*:

$$\begin{aligned}\dot{A} = & \left(\frac{1}{2}\mu - i\frac{\mu^2}{8\omega_1} \right) A + \frac{3}{2} \left[i\frac{c}{\omega_1} - \frac{3}{4}\frac{c}{\omega_1^2}\mu - (b_0 + b_1)\omega_1^2 \right] A^2 \bar{A} \\ & + \left[-\frac{3}{2}c(b_0 + b_1) - i\frac{15}{16}\frac{c^2}{\omega_1^3} + \frac{9}{16}i\omega_1^3(b_0 + b_1)^2 \right. \\ & \left. + 9ib_0^2\omega_1^5 \left(\frac{1}{2}\frac{1}{\omega_2^2 - 9\omega_1^2 + 3i\xi\omega_1} + \frac{1}{\omega_2^2 - \omega_1^2 + i\xi\omega_1} - \frac{1}{2}\frac{1}{\omega_2^2 - \omega_1^2 - i\xi\omega_1} \right) \right] A^3 \bar{A}^2\end{aligned}$$

Using the polar form:

$$A(t) := \frac{1}{2} a(t) e^{i\theta(t)}$$

and separating the real and imaginary parts, two real *bifurcation equations* follow.

- Amplitude equation:

$$\begin{aligned}\dot{a} = & \frac{1}{2} \mu a - \left[\frac{3}{8} (b_0 + b_1) \omega_1^2 - \frac{3}{16} \frac{c}{\omega_1^2} \mu \right] a^3 \\ & + \left[-\frac{3}{32} c (b_0 + b_1) + \frac{27}{32} b_0^2 \xi \omega_1^6 \left(\frac{1}{(\omega_2^2 - 9\omega_1^2)^2 + 9\xi^2 \omega_1^2} + \frac{1}{(\omega_2^2 - \omega_1^2)^2 + \xi^2 \omega_1^2} \right) \right] a^5\end{aligned}$$

- phase-equation:

$$\begin{aligned}
a\dot{\vartheta} = & -\frac{1}{8}\frac{\mu^2}{\omega_1}a + \frac{3}{8}\frac{c}{\omega_1}a^3 \\
& + [\frac{9}{256}(b_0 + b_1)^2\omega_1^3 - \frac{15}{256}\frac{c^2}{\omega_1^3} \\
& - \frac{9}{32}b_0^2\omega_1^7(\frac{9}{(\omega_2^2 - 9\omega_1^2)^2 + 9\xi^2\omega_1^2} + \frac{1}{(\omega_2^2 - \omega_1^2)^2 + \xi^2\omega_1^2}) \\
& + \frac{9}{32}b_0^2\omega_1^5\omega_2^2(\frac{1}{(\omega_2^2 - 9\omega_1^2)^2 + 9\xi^2\omega_1^2} + \frac{1}{(\omega_2^2 - \omega_1^2)^2 + \xi^2\omega_1^2})]a^5
\end{aligned}$$

□ **Note:** The essential dynamics of the original system is governed by a one-dimensional amplitude-equation.

- Response of the system:

$$\begin{aligned}
 x &= a(t) \cos(\Phi(t)) + a^3(t) \left[\frac{1}{32} \frac{c}{\omega_1^2} \cos(3\Phi(t)) + \frac{1}{32} (b_0 + b_1) \omega_1 \sin(3\Phi(t)) \right] + \dots \\
 y &= \frac{3}{4} a^3(t) \left[\frac{b_0 \xi \omega_1^4}{(\omega_2^2 - \omega_1^2)^2 + \xi^2 \omega_1^2} \cos(\Phi(t)) - \frac{b_0 \xi \omega_1^4}{(\omega_2^2 - 9\omega_1^2)^2 + 9\xi^2 \omega_1^2} \cos(3\Phi(t)) \right. \\
 &\quad \left. + \frac{b_0 \omega_1^3 (\omega_1^2 - \omega_2^2)}{(\omega_2^2 - \omega_1^2)^2 + \xi^2 \omega_1^2} \sin(\Phi(t)) - \frac{b_0 \omega_1^3 (9\omega_1^2 - \omega_2^2)}{(\omega_2^2 - 9\omega_1^2)^2 + 9\xi^2 \omega_1^2} \sin(3\Phi(t)) \right] + \dots
 \end{aligned}$$

where:

$$\Phi(t) := \omega_1 t + \theta(t).$$

■ Steady solutions:

$$a = a_s = \text{const}, \quad \dot{\theta} =: \kappa = \text{const}$$

are limit cycles, of amplitude a_s and (nonlinear) frequency $\dot{\Phi} = \omega_l + \kappa = \text{const}$

- Remarks
 - (a) At leading order, only the active coordinate x , contributes to the motion.
 - (b) At a higher-order, also the passive coordinate y is triggered. This *does not contribute with its own free evolution*, but rather *is forced by the active x -coordinate*
 - (c) Taking into account passive coordinates, *does not increase* the dimension of the amplitude equations, but just gives a more accurate description of the dynamics

2.NON-RESONANT DOUBLE-HOPF BIFURCATION

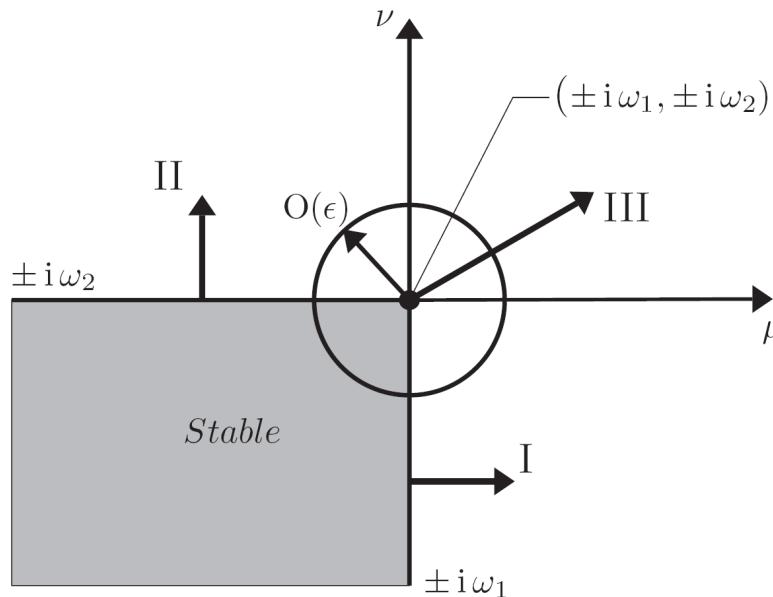
- When, for a critical combination of the parameters, the generating system admits two or more pairs $\pm i\omega_k$ ($k = 1, 2, \dots$) of imaginary eigenvalues, a *multiple Hopf bifurcation* takes place.
- More modal components must be considered in the generating solution; the response is said *multi-modal*.
- The response is non-resonant if *none of the active frequencies ω_k can be expressed as a linear combination with integer coefficients of the remaining active frequencies*.

EXAMPLE: TWO COUPLED RAYLEIGH-DUFFING OSCILLATORS, BOTH UNSTABLE

$$\begin{cases} \ddot{x} - \mu \dot{x} + \omega_1^2 x + b_1 \dot{x}^3 + cx^3 - b_0(\dot{y} - \dot{x})^3 = 0 \\ \ddot{y} - \nu \dot{y} + \omega_2^2 y + b_2 \dot{y}^3 + cy^3 + b_0(\dot{y} - \dot{x})^3 = 0 \end{cases}$$

The linear frequencies are incommensurable: $\omega_2 \neq r\omega_1, \forall r \in \mathbb{Q}$

- Linear stability diagram:



Linear stability diagram for a system undergoing double-Hopf bifurcation.

- Rescaling:

$$(\mu, \nu) \rightarrow (\varepsilon\mu, \varepsilon\nu), (x, y) \rightarrow (\varepsilon^{1/2}x, \varepsilon^{1/2}y)$$

- Series expansions:

$$\begin{pmatrix} x(t; \varepsilon) \\ y(t; \varepsilon) \end{pmatrix} = \begin{pmatrix} x_0(t_0, t_1, t_2, \dots) \\ y_0(t_0, t_1, t_2, \dots) \end{pmatrix} + \varepsilon \begin{pmatrix} x_1(t_0, t_1, t_2, \dots) \\ y_1(t_0, t_1, t_2, \dots) \end{pmatrix} + \varepsilon^2 \begin{pmatrix} x_2(t_0, t_1, t_2, \dots) \\ y_2(t_0, t_1, t_2, \dots) \end{pmatrix} + \dots$$

$$\frac{d}{dt} = d_0 + \varepsilon d_1 + \varepsilon^2 d_2 + \dots, \quad \frac{d^2}{dt^2} = d_0^2 + 2\varepsilon d_0 d_1 + \varepsilon^2 (d_1^2 + 2d_0 d_2) + \dots$$

where $t_k := \varepsilon^k t_k$ and $d_k := \partial / \partial t_k$.

- Perturbation equations:

$$\varepsilon^0 : \begin{cases} d_0^2 x_0 + \omega_1^2 x_0 = 0 \\ d_0^2 y_0 + \omega_2^2 y_0 = 0 \end{cases}$$

$$\varepsilon^1 : \begin{cases} d_0^2 x_1 + \omega_1^2 x_1 = -2d_0 d_1 x_0 + \mu d_0 x_0 - b_1 (d_0 x_0)^3 - cx_0^3 + b_0 (d_0 y_0 - d_0 x_0)^3 \\ d_0^2 y_1 + \omega_2^2 y_1 = -2d_0 d_1 y_0 + \nu d_0 y_0 - b_2 (d_0 y_0)^3 - cy_0^3 - b_0 (d_0 y_0 - d_0 x_0)^3 \end{cases}$$

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- Generating solution:

$$\begin{cases} x_0 = A_1(t_1, t_2, \dots) e^{i\omega_1 t_0} + c.c. \\ y_0 = A_2(t_1, t_2, \dots) e^{i\omega_2 t_0} + c.c. \end{cases}$$

- ϵ -order:

➤ equations:

Cubic terms produce harmonics $(\omega_1, \omega_2; 3\omega_1, 3\omega_2, \omega_2 \pm 2\omega_1, 2\omega_2 \pm \omega_1)$; among them, only ω_1 in the first equation and ω_2 in the second equation are resonant:

$$\begin{cases} d_0^2 x_1 + \omega_1^2 x_1 = f_{1,1} e^{i\omega_1 t_0} + NRT + c.c. \\ d_0^2 y_1 + \omega_2^2 y_1 = f_{2,2} e^{i\omega_2 t_0} + NRT + c.c. \end{cases}$$

where:

$$f_{1,1} := -2i\omega_1 d_1 A_1 + i\omega_1 \mu A_1 - 3[c + i(b_0 + b_1)\omega_1^3] A_1^2 \bar{A}_1 - 6b_0 \omega_1 \omega_2^2 A_1 A_2 \bar{A}_2$$

$$f_{2,2} := -2i\omega_2 d_1 A_2 + i\nu \omega_2 A_2 - 3[c + i(b_0 + b_2)\omega_2^3] A_2^2 \bar{A}_2 - 6b_0 \omega_1^2 \omega_2 A_1 \bar{A}_1 A_2$$

➤ Zeroing the secular terms requires $f_{1,1} = f_{2,2} = 0$, from which:

$$\begin{cases} d_1 A_1 = \frac{1}{2} \mu A_1 + \frac{3}{2} [i \frac{c}{\omega_1} - (b_1 + b_0) \omega_1^2] A_1^2 \bar{A}_1 - 3b_0 \omega_2^2 A_1 A_2 \bar{A}_2 \\ d_1 A_2 = \frac{1}{2} \nu A_2 + \frac{3}{2} [i \frac{c}{\omega_2} - (b_2 + b_0) \omega_2^2] A_2^2 \bar{A}_2 - 3b_0 \omega_1^2 A_1 A_2 \bar{A}_1 \end{cases}$$

- First-order solution:

The previous equations are multiplied by $\varepsilon^{3/2}$ and use is made of the inverse transformations $\varepsilon^{1/2} A_k \rightarrow A_k$, $\varepsilon(\mu, \nu) \rightarrow (\mu, \nu)$, $\varepsilon d_1 \rightarrow D$, so that $d_1 A_k \equiv \dot{A}_k$. By using the polar forms:

$$A_k(t) := \frac{1}{2} a_k(t) e^{i\theta_k(t)} \quad k=1, 2$$

four real bifurcation equations follow.

- Amplitude modulation equations:

$$\begin{cases} \dot{a}_1 = \frac{1}{2}\mu a_1 - \frac{3}{8}(b_0 + b_1)\omega_1^2 a_1^3 - \frac{3}{4}b_0\omega_2^2 a_1 a_2^2 \\ \dot{a}_2 = \frac{1}{2}\nu a_2 - \frac{3}{8}(b_0 + b_2)\omega_2^2 a_2^3 - \frac{3}{4}b_0\omega_1^2 a_1^2 a_2 \end{cases}$$

- Phase-modulation equations:

$$\begin{cases} a_1 \dot{\theta}_1 = \frac{3}{8} \frac{c}{\omega_1} a_1^3 \\ a_2 \dot{\theta}_2 = \frac{3}{8} \frac{c}{\omega_2} a_2^3 \end{cases}$$

□ **Note:** in the non-resonant case, the real-amplitude equations are uncoupled from the phase-equations . Therefore, the essential dynamics of the system is governed by the reduced set of two (RAME) equations.

■ Steady solutions, bifurcation chart and bifurcation diagrams

- Steady motions:

Are the fixed points $a_1 = a_{1s} = \text{const}$, $a_2 = a_{2s} = \text{const}$. Assume $b_1 = b_2 =: b > 0$, $\beta := b_0/b > 0$. The steady motions are solutions of:

$$\begin{cases} a_1 \left[\frac{1}{2} \frac{\mu}{b} - \frac{3}{8} (1 + \beta) \omega_1^2 a_1^2 - \frac{3}{4} \beta \omega_2^2 a_2^2 \right] = 0 \\ a_2 \left[\frac{1}{2} \frac{\nu}{b} - \frac{3}{8} (1 + \beta) \omega_2^2 a_2^2 - \frac{3}{4} \beta \omega_1^2 a_1^2 \right] = 0 \end{cases}$$

- Four essentially different solutions, ($s = T, P_1, P_2, Q$):

$$(T): \quad a_{1T} = 0, a_{2T} = 0, \forall (\mu, \nu)$$

$$(P_1): \quad a_{1P} = \frac{1}{\omega_1} \sqrt{\frac{4\mu}{3b(1+\beta)}}, \quad a_{2P} = 0, \quad \forall \nu$$

$$(P_2): \quad a_{1P} = 0, \quad a_{2P} = \frac{1}{\omega_2} \sqrt{\frac{4\nu}{3b(1+\beta)}}, \quad \forall \mu$$

$$(Q): \quad a_{1Q} = \frac{2}{\omega_1} \sqrt{\frac{2\beta\nu-(1+\beta)\mu}{3b(3\beta^2-2\beta-1)}}, \quad a_{2Q} = \frac{2}{\omega_2} \sqrt{\frac{2\beta\mu-(1+\beta)\nu}{3b(3\beta^2-2\beta-1)}}$$

- Meaning of the solutions:

(T) is the *trivial* solution, which corresponds to the equilibrium position of the system.

(P_1) is the mono-modal *periodic* a_1 -solution:

$$x = a_{1P} \cos(\Omega_1 t + \theta_{10}), \quad y = 0, \quad \Omega_1 := \omega_1 + \frac{3}{8} \frac{c}{\omega_1} a_{1P}^2$$

(P_2) is the mono-modal *periodic* a_2 -solution:

$$x = 0, \quad y = a_{2P} \cos(\Omega_2 t + \theta_{20}), \quad \Omega_2 := \omega_2 + \frac{3}{8} \frac{c}{\omega_2} a_{2P}^2$$

(Q) is a bimodal *quasi-periodic* solution:

$$x = a_{1Q} \cos(\Omega_1 t + \theta_{10}), \quad y = a_{2Q} \cos(\Omega_2 t + \theta_{20}), \quad \Omega_1 := \omega_1 + \frac{3c}{8\omega_1} a_{1Q}^2, \quad \Omega_2 := \omega_2 + \frac{3c}{8\omega_2} a_{2Q}^2$$

since ω_1 and ω_2 are incommensurable.

- Existence domains of the solutions

Since the amplitudes are real and positive:

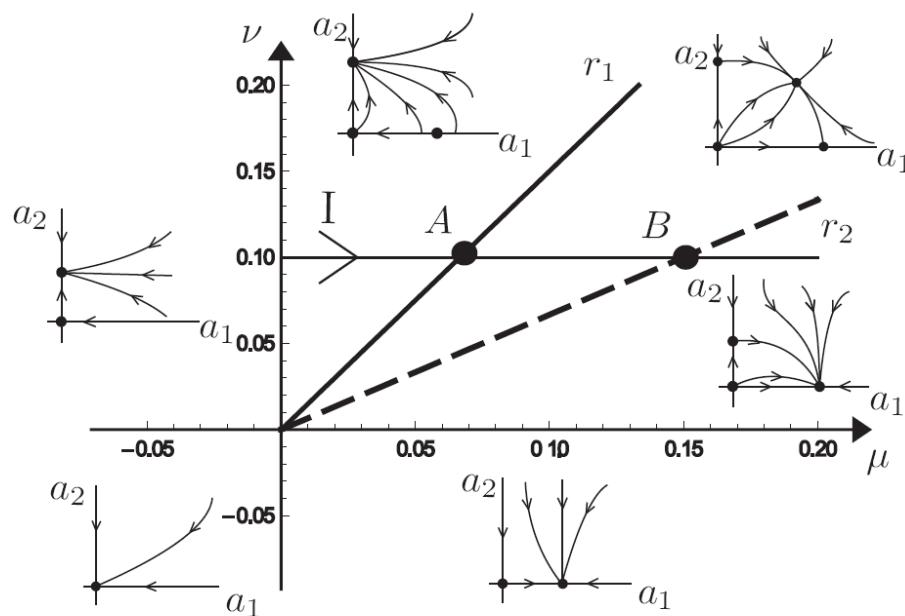
- the T -solution exists in the whole plane
- the P_1 -solution is defined in the $\mu \geq 0$ half-plane
- the P_2 -solution in the $\nu \geq 0$ half-plane
- the Q -solution requires:

$$\frac{2\beta}{1+\beta} \mu < \nu < \frac{1+\beta}{2\beta} \mu \quad \text{if } \beta < 1$$

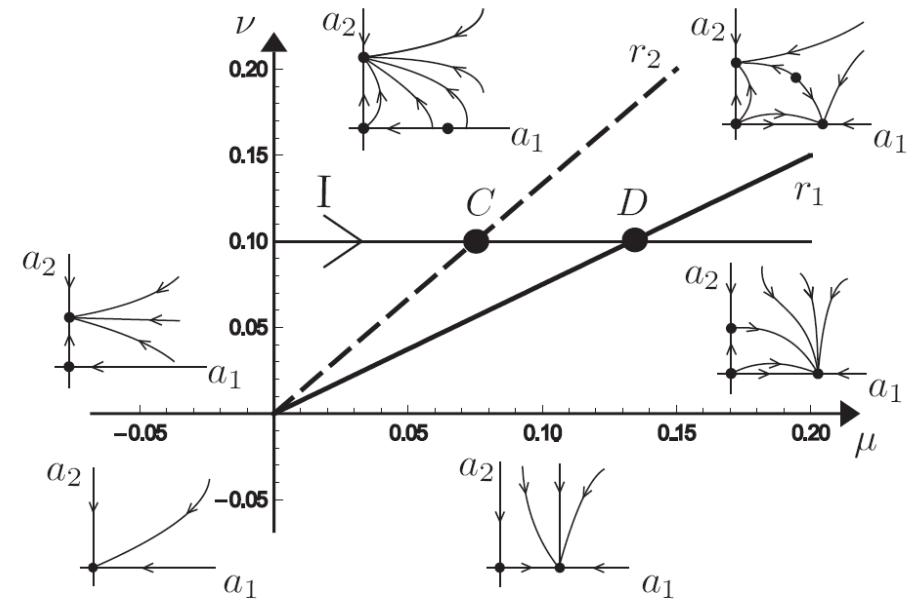
$$\frac{1+\beta}{2\beta} \mu < \nu < \frac{2\beta}{1+\beta} \mu \quad \text{if } \beta > 1$$

i.e. it exists in the sector bounded by $r_1 := \{(\mu, \nu) | \nu = (1 + \beta)/(2\beta)\mu\}$,
 $r_2 := \{(\mu, \nu) | \nu = (2\beta)/(1 + \beta)\mu\}$.

- At r_1 : $a_{1Q} = 0, a_{2Q} = a_{2P}$; at r_2 : $a_{1Q} = a_{1P}, a_{2Q} = 0$
- r_1 and r_2 are *bifurcation loci*, where a quasi-periodic motion bifurcates from a periodic motion.



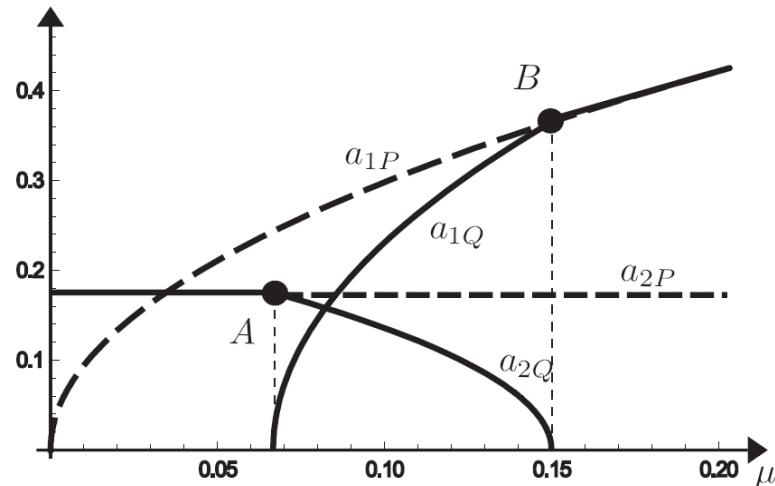
(a)



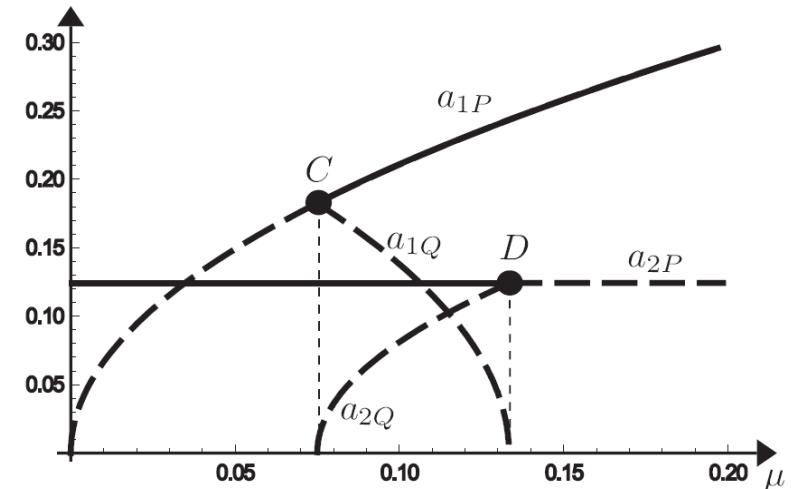
(b)

Bifurcation chart for: (a) $\beta = 1/2$ and (b) $\beta = 2$

- Planar bifurcation diagrams:



(a)



(b)

Bifurcation diagrams for (a) $\beta = 1/2$ and (b) $\beta = 2$; $\nu = 0.1$, $\omega_1 = 1$, $\omega_2 = 1.7$; ---- stable, --- unstable

- Stability of steady-solutions

Variation of the amplitude equations:

$$\begin{pmatrix} \delta \dot{a}_1 \\ \delta \dot{a}_2 \end{pmatrix} = \mathbf{J}_s \begin{pmatrix} \delta a_1 \\ \delta a_2 \end{pmatrix}$$

where:

$$\mathbf{J}_s := \begin{pmatrix} \frac{\mu}{2} - \frac{9}{8} b\omega_1^2 (1 + \beta) a_{1s}^2 - \frac{3}{4} \beta b\omega_2^2 a_{2s}^2 & -\frac{3}{2} \beta b\omega_2^2 a_{1s} a_{2s} \\ -\frac{3}{2} \beta b\omega_1^2 a_{1s} a_{2s} & \frac{\nu}{2} - \frac{9}{8} b\omega_2^2 (1 + \beta) a_{2s}^2 - \frac{3}{4} \beta b\omega_1^2 a_{1s}^2 \end{pmatrix}$$

is the Jacobian evaluated at the steady-solution s .

In order that s is (asymptotically) stable, both the eigenvalues of \mathbf{J}_s must have negative real part.

For each solution:

- Trivial solution ($s=T$): $\mathbf{J}_T = \text{diag}[\mu/2, \nu/2]$, i.e. the trivial solution is stable in the third quadrant and unstable elsewhere;
- Periodic solutions ($s=P_1, P_2$):

$$\mathbf{J}_{P_1} = \text{diag}\left[-\mu, \frac{\nu}{2} - \frac{\beta\mu}{1+\beta}\right], \quad \mathbf{J}_{P_2} = \text{diag}\left[-\nu, \frac{\mu}{2} - \frac{\beta\nu}{1+\beta}\right]$$

An eigenvalue is always negative; the other vanishes at the straight lines r_2 and r_1 . The P_1 -solution is stable *below* r_2 , and the P_2 -solution is stable *above* r_1 .

(continue)

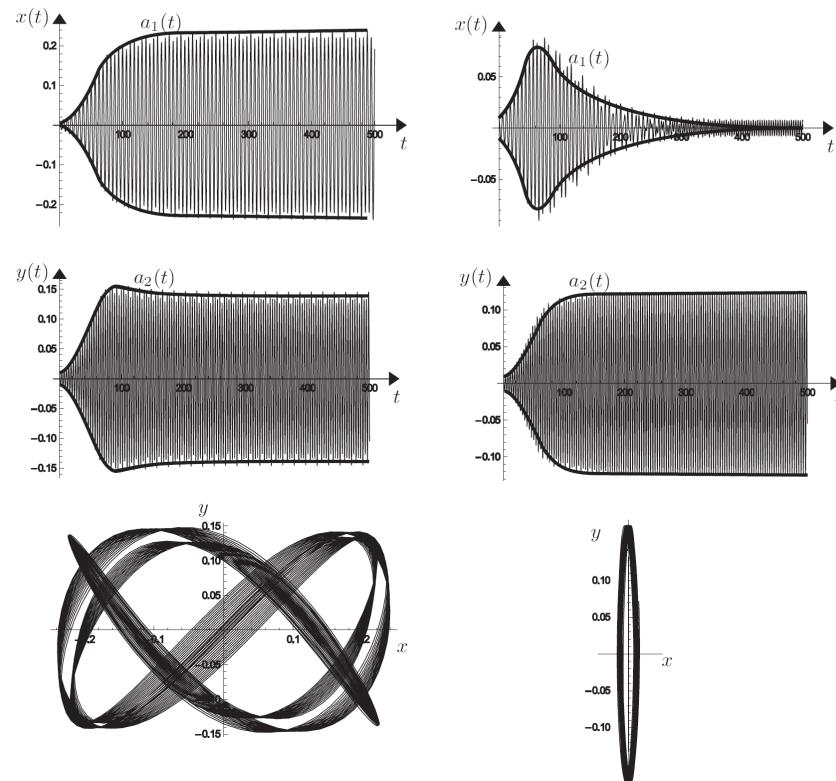
➤ Quasi-periodic solution ($s=Q$):

$$\text{tr}[\mathbf{J}_Q] = -\frac{(1+\beta)(\mu+\nu)}{1+3\beta}, \quad \det[\mathbf{J}_Q] = \frac{2\beta\nu-(1+\beta)\mu}{\beta-1} \frac{2\beta\mu-(1+\beta)\nu}{1+3\beta}$$

- ✓ For asymptotic stability $\text{tr}[\mathbf{J}_Q] < 0, \det[\mathbf{J}_Q] > 0$ simultaneously.
- ✓ $\text{tr}[\mathbf{J}_Q] < 0$ in any points of the existence domain;
- ✓ $\det[\mathbf{J}_Q] = 0$ at r_1 and r_2 ; inside the domain:
 $\det[\mathbf{J}_Q] > 0$ when $\beta < 1$ (Q -solution stable),
 $\det[\mathbf{J}_Q] < 0$ when $\beta > 1$ (Q -solution unstable).

■ Numerical integrations

Projection of the orbits onto the bi-dimensional (x, y) configuration-plane.
 Parameters are in the Q -region. Comparison between numerical solutions of
 the original equations and the RAME.



Numerical solutions for (x, y) -coordinates and (a_1, a_2) -amplitudes ; (a) $\beta = 1/2$, (b) $\beta = 2$;
 $\mu = 0.1, \nu = 0.1, \omega_1 = 1, \omega_2 = 1.7, c = 1$. Orbits refer to the steady-regime.

3. STATIC-DYNAMIC INTERACTION: THE DIVERGENCE-HOPF BIFURCATION

The MSM can be used also for multiple static-dynamic bifurcations. An example is given here.

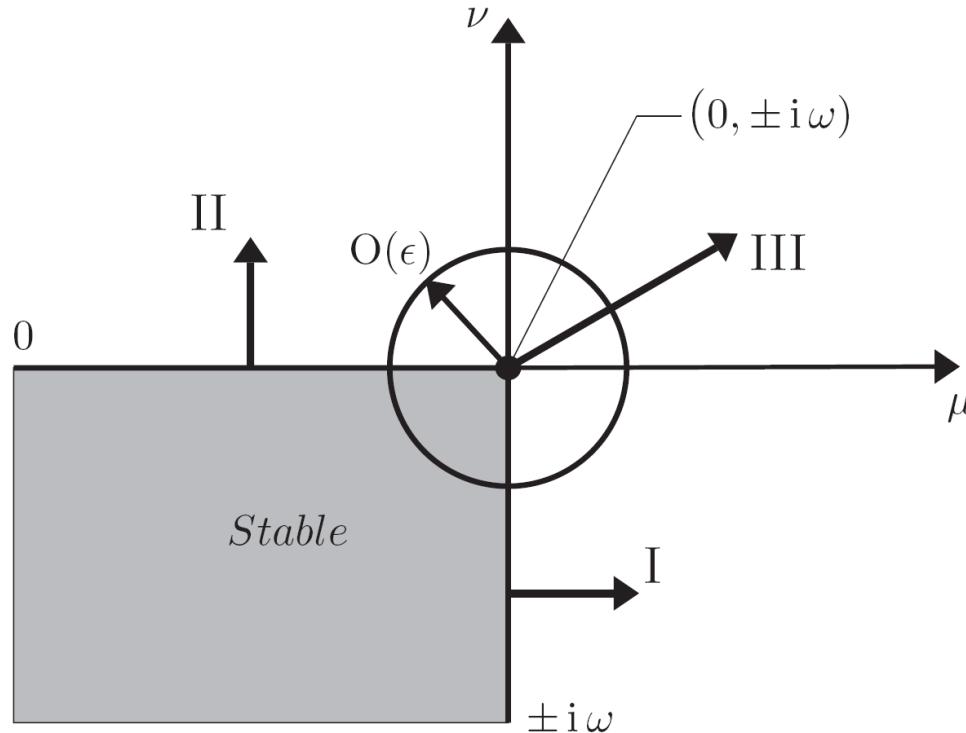
■ EXAMPLE: TWO COUPLED RAYLEIGH-DUFFING OSCILLATORS, BOTH UNSTABLE

The x -oscillator undergoes a *dynamic bifurcation*, governed by the parameter μ ; the y -oscillator, suffers a *static bifurcation*, governed by the parameter ν :

$$\begin{cases} \ddot{x} - \mu \dot{x} + \omega^2 x + b_1 \dot{x}^3 + cx^3 - b_0(y-x)^2(\dot{y}-\dot{x}) - c_0(y-x)^3 = 0 \\ \ddot{y} + \xi \dot{y} - \nu y + b_2 \dot{y}^3 + cy^3 + b_0(y-x)^2(\dot{y}-\dot{x}) + c_0(y-x)^3 = 0 \end{cases}$$

where $\xi = O(1) > 0$.

- Discussion on stability:



Linear stability diagram for the two Rayleigh-Duffing coupled oscillators undergoing divergence-Hopf bifurcation..

- Rescaling:

$$(\mu, \nu) \rightarrow (\varepsilon\mu, \varepsilon\nu), \quad (x, y) \rightarrow (\varepsilon^{1/2}x, \varepsilon^{1/2}y)$$

- Series expansions:

$$\begin{pmatrix} x(t; \varepsilon) \\ y(t; \varepsilon) \end{pmatrix} = \begin{pmatrix} x_0(t_0, t_1, t_2, \dots) \\ y_0(t_0, t_1, t_2, \dots) \end{pmatrix} + \varepsilon \begin{pmatrix} x_1(t_0, t_1, t_2, \dots) \\ y_1(t_0, t_1, t_2, \dots) \end{pmatrix} + \varepsilon^2 \begin{pmatrix} x_2(t_0, t_1, t_2, \dots) \\ y_2(t_0, t_1, t_2, \dots) \end{pmatrix} + \dots$$

$$\frac{d}{dt} = d_0 + \varepsilon d_1 + \varepsilon^2 d_2 + \dots, \quad \frac{d^2}{dt^2} = d_0^2 + 2\varepsilon d_0 d_1 + \varepsilon^2 (d_1^2 + 2d_0 d_2) + \dots$$

where $t_k := \varepsilon^k t_k$ and $d_k := \partial / \partial t_k$.

- Perturbation equations:

$$\varepsilon^0 : \begin{cases} d_0^2 x_0 + \omega^2 x_0 = 0 \\ d_0^2 y_0 + \xi d_0 y_0 = 0 \end{cases}$$

$$\varepsilon^1 : \begin{cases} d_0^2 x_1 + \omega^2 x_1 = -2d_0 d_1 x_0 + \mu d_0 x_0 - b_1 (d_0 x_0)^3 - c x_0^3 \\ \quad \quad \quad + b_0 (y_0 - x_0) (d_0 y_0 - d_0 x_0)^2 + c_0 (y_0 - x_0)^3 \\ d_0^2 y_1 + \xi d_0 y_1 = -2d_0 d_1 y_0 - \xi d_1 y_0 + \nu y_0 - b_2 (d_0 y_0)^3 - c y_0^3 \\ \quad \quad \quad - b_0 (y_0 - x_0) (d_0 y_0 - d_0 x_0)^2 - c_0 (y_0 - x_0)^3 \end{cases}$$

- Generating solution:

$$\begin{cases} x_0 = A_1(t_1, t_2, \dots) e^{i\omega t_0} + c.c. \\ y_0 = a_2(t_1, t_2, \dots) \end{cases}$$

where $A_1 \in \mathbb{C}, a_2 \in \mathbb{R}$. The x -oscillator experiences a harmonic motion, slowly modulated; the y -oscillator rests in a non-trivial equilibrium position, also modulated.

- ϵ -order:

➤ equations:

$$\begin{cases} d_0^2 x_1 + \omega^2 x_1 = f_{1,1} e^{i\omega t_0} + NRT + c.c. \\ d_0^2 y_1 + \xi d_0 y_1 = f_{2,0} + (NRT + c.c.) \end{cases}$$

where the resonant excitations terms are:

$$f_{1,1} := -2i\omega d_1 A_1 + i\omega u A_1 - [3(c + c_0) + ib_0\omega + 3ib_1\omega^3] A_1^2 \bar{A}_1 - (3c_0 + ib_0\omega) A_1 a_2^2$$

$$f_{2,0} := -\xi d_1 a_2 + \nu A_2 - (c + c_0) a_2^3 - 6c_0 A_1 \bar{A}_1 a_2$$

➤ Removing secular terms requires: $f_{1,1} = 0$ and $f_{2,0} = 0$, from which:

$$d_1 A_1 = \frac{1}{2} \mu A_1 + \frac{1}{2} \left[\frac{3}{\omega} i(c + c_0) - b_0 - 3b_1 \omega^2 \right] A_1^2 \bar{A}_1 - (3c_0 + i b_0 \omega) A_1 a_2^2$$

$$d_1 a_2 = \frac{1}{\xi} [\nu A_2 - (c + c_0) a_2^3 - 6c_0 A_1 \bar{A}_1 a_2]$$

- Parameter reabsorbing:

By multiplying the equations by $\varepsilon^{3/2}$ and using $\varepsilon^{1/2} A_1 \rightarrow A_1, \varepsilon^{1/2} a_2 \rightarrow a_2$, together with $\varepsilon(\mu, \nu) \rightarrow (\mu, \nu)$, $\varepsilon d_1 \rightarrow D$, and by expressing A_1 in the polar form, three real bifurcation equations follows.

➤ Two amplitude-equations:

$$\begin{cases} \dot{a}_1 = \frac{1}{2}\mu a_1 - \frac{1}{8}(b_0 + 3b_1\omega_1^2)a_1^3 - \frac{1}{2}b_0 a_1 a_2^2 \\ \dot{a}_2 = \frac{1}{\xi}\nu a_2 - \frac{1}{\xi}(c + c_0)\omega_2^2 a_2^3 - \frac{3}{2\xi}c_0 a_1^2 a_2 \end{cases}$$

➤ One phase equation:

$$a_1 \dot{\theta}_1 = \frac{3}{8} \frac{c + c_0}{\omega} a_1^3 + \frac{3}{2} \frac{c_0}{\omega} a_1 a_2^2$$

□ **Note:** The amplitude equations governing the non-resonant double-Hopf bifurcation and the divergence-Hopf bifurcations have the same (normal) form.